

3D Concrete Printing - from material design to extrusion

Annual Civil Engineering Workshop at Ecole Centrale de Lille July, 2017



3D Concrete Printing



MATERIALS



3D Concrete Printing refers to the process used to synthesize a 3D model in successive layers of material to create an object, e.g. a concrete wall

Robot-based 3D Printing Process:



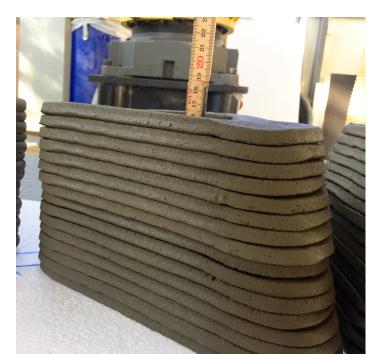






Fresh concrete is the filament:

- Similar materials to that of concrete
- Max. particle size (up to 2.0 mm)
- Concrete admixtures



Material challenges:

- Pumpability vs. Buildability
- Concrete rheology (fresh state)











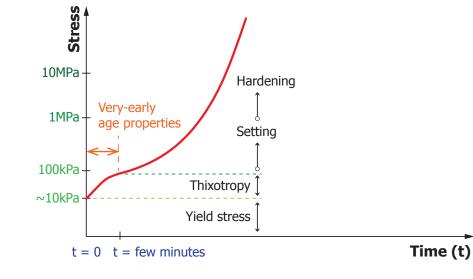


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Concrete properties and mix design



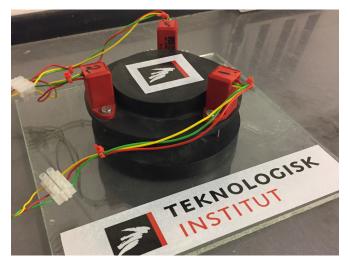
- Cement hydration
- Concrete admixtures
- Strength development
- Drying shrinkage ...



Nothing we do not know... But now we need all of it at once and with high precision

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Test device - layer deformation measurements









Buildability of fresh concrete (without the use of accelerators)











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Batch process:

- Concrete composition is constant
- *Fresh-state properties* can be adjusted by adding admixtures while printing

Continuous mixing:

- Concrete composition is adjustable
- *Fresh and hardened-state properties* can be adjusted while printing





Source: MTec



Mixing plant at DTI's Concrete Centre



Increase robustness of the production process

• Enable the production

concrete elements

of functionally-graded





Feedback system in a continuous mixing production process:

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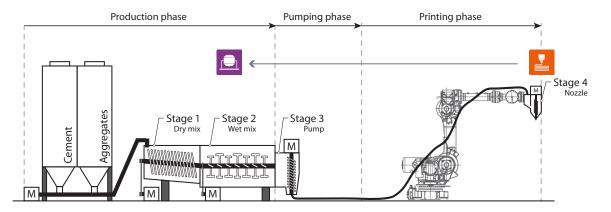












Funtionally-graded concrete sample



Source: MIT







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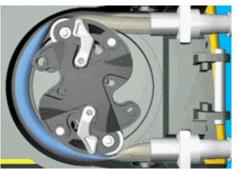
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Peristaltic concrete pump:

- Pulsating extrusion (poor controllability)
- Large equipment for initial tests





Progressive cavity pump:

- Controlled extrusion (rotor-stator)
- Enables high-resolution printing
- Low oozing (preditable material flow)
- Suitable for high-viscosity materials



Source: PCM

Endless-piston principle (True positive displacement)



Source: PCM





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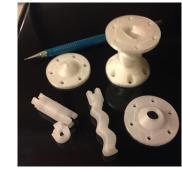
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Progressive cavity pump

3D Printed prototype

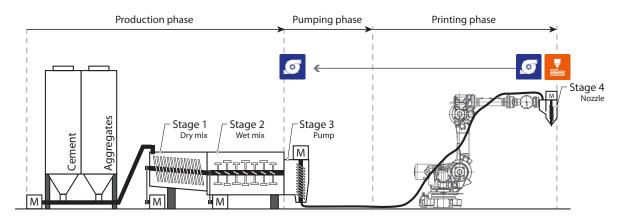


DTI's progressive cavity pump





• Increase controlability and reliability of the printing process









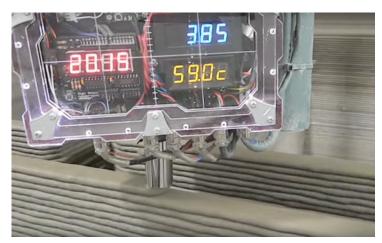
"Passive" robot nozzle:

The extrusion is controlled by a pump and the robot nozzle works as a dispenser that defines the shape of the printed layers.



"Active" robot nozzle:

The extrusion is controlled at the nozzle by a pump, enabling great precision and addition of admixtures during extrusion.



Source: Total Kustom







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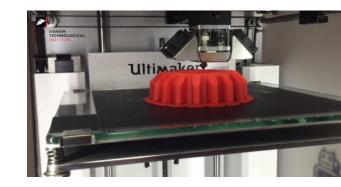


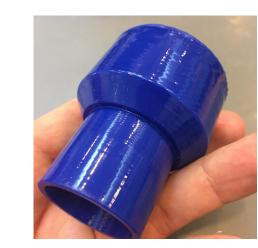
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Nozzle experiments (3D Printed Nozzles)







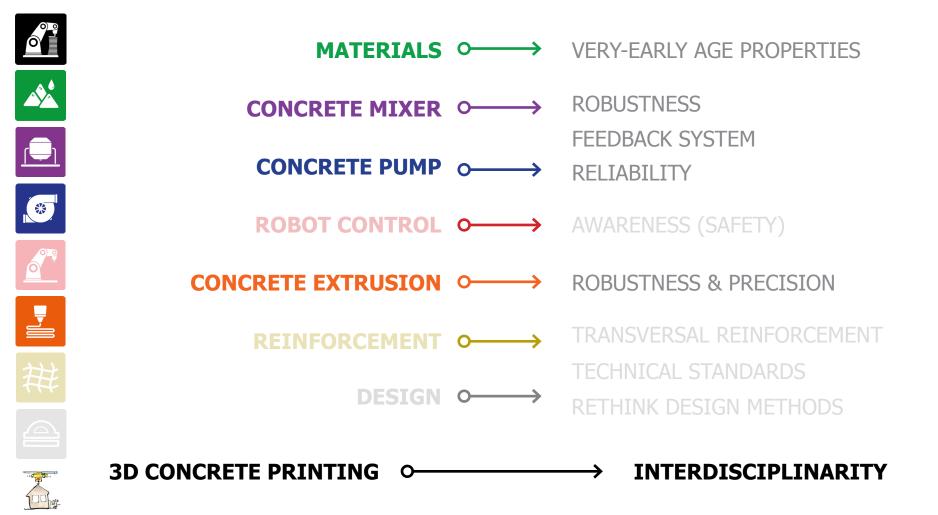
Concrete buildability = f(properties at very-early age, e.g. yield stress)



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3DCP: Knowledge Network











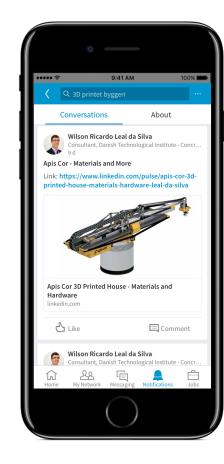








3D Printet Byggeri on LinkedIn



Overview of the Workshop on Digital Fabrication with Concrete at ETH Zurich

ublished on February 1, 2017



Interdisciplinarity is a crucial element in digital fabrication applied to construction. The workshop on Digital Fabrication with Concrete as well as the 2nd meeting of the RILEM TC on Digital Fabrication with Cement-based Materials, and other events, as well as my personal experience as a member of the "3D Printet Byggen" project at the Concrete Centre - Danish Technological Institute, made this evident. Not surprisingly, this was a unanimous conclusion of the workshop's participants undoubtedly because all of the ongoing R&D projects presented during the workshop are a result of the collaboration between architects, engineers, materials scientists and roboticists, to mention a few. I take the liberty to quote Prof. Flatt (ETH Zurich), who said:

> ... "To succeed in research on digital fabrication with cement-based materials, interdisciplinarity is key" ...

In addition, the workshop participants agreed that **R&D projects probably will find an** easier path to industrial applications if real-scale applications are already considered at the development stage. For example, several factors influence the 3D Concrete Printing process (e.g. materials, production process, controlling, among others), and limiting R&D efforts to small-scale applications may masquerade real-scale conditions and factors that cannot be simulated in the laboratory.

Try to imagine simulating a rather chaotic system such as a construction site - I would regard it as a living organism. Despite all efforts to keep it neat and organised, things happen that cannot be predicted or replicated, so real-scale tests help to build confidence on the technical development, speeding up industrial uptake. The presentation by Prof. Buchli (ETH Zurich) addressed exactly that, i.e. "Robotics Challenges in Digital Fabrication in Architecture and Construction", with a particular focus on **humanmachine interaction and sensing for closed loop control**. Details aside, I am listing

Thank you for your attention!

Reference to this presentation:

Leal da Silva, W.R. (2017). 3D Concrete Printing - from material design to extrusion. [Presentation Slides] Retrieved from Danish Technological Institute website: https://www.dti.dk/projects/3d-printed-buildings/36993

Wilson Ricardo Leal da Silva

Consultant, Civil Engineer, Ph.D. Concrete Centre Mobile +45 72 20 10 34 wrls@teknologisk.dk

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